

Invest in the Future

Instruction Plan

Syllabus – Primary Labs



SYLLABUS I – BASIC MODULE

Level I

- Basic Electronics I

 1.1.Paper Circuits
 1.2.Introduction to Breadboard
 1.3.Series and Parallel Circuits
 1.4.Traffic Light Circuit with Switch
- Mechanics I
 2.1.DIY Grabber
 2.2.Robotics Arm
- 3D Design and Printing I
 3.1.Design and print a 3D Keychain
 3.2.Design and 3D Print a Cup
- Data Visualization
 4.1.How do I spend my day?
- Design and Entrepreneurial Thinking I
 5.1.Design Thinking and Prototyping (Redesign Auto Rickshaw)
 5.2.Final Project: Design Thinking to make classroom environment improvements

Level II

- 1. Basic Electronics II
 - 1.1.Automatic Street Light using LDR
 - 1.2.Solar Powered Electric Fan
 - 1.3.Basic of Arduino I
 - 1.4.Basic of Arduino II
- Mechanics II
 2.1.Hydraulic Lift
 2.2.Bug Bot
- 3. 3D Design and Printing II
 3.1.Design and 3D Print a Rocket
 - 3.2.Design and 3D Print a Simple Mobile Holder
- 4. Design and Entrepreneurial Thinking II
- 4.1.Design a Room for Elderly 4.2.Final Project: Ensure Water Conservation

Level III

- 1. Basic Electronics III
 - 1.1.Ohm's Law and How to use a Multimeter
 - 1.2.Seven 7 Segment Display
 - 1.3.PCB Etching
 - 1.4.Sensors and Actuators using Arduino
- 2. Internet of Things
 - 2.1.ESP32 Basics
 - 2.2.Interfacing LDR with ESP32
 - 2.3.Control an LED using Mobile App
 - 2.4.IoT Plant Monitoring using ESP32
- 3D Design and Printing III
 3.1.Design and 3D Print a Spanner
 3.2.Design and 3D Print a Walking Robot



- 4. Woodworking
 - 4.1.Introduction to Woodworking
 - 4.2.Make your own Birdhouse
- Design and Entrepreneurial Thinking III
 5.1.Sustainable Home Model
 5.2.Final Project: Sustainable Village Model

SYLLABUS II – ADVANCE MODULE

AIoT Integration

- AIoT Integration About the Program
 1.1.Introduction of Artificial Intelligence Curriculum
 - 1.2.AIoT Integration Joint Initiative
 - 1.2.1. Rational for AIoT Integrating in Curriculum program
 - 1.2.2. Objectives of the program
- 2. Introduction of Tinkering and Artificial Intelligence 2.1.Introduction to Tinkering and stages of Tinkering 2.2.Introduction to Artificial Intelligence
- 3. Developing AI and Tinkering Integration Ecosystem
- Integrating AI and Tinkering across Curriculum
 Integrating AI and Tinkering in Formal Subject Pedagogies
 AI and Tinkering Integration alignment with Skill Development
- Implementation process and Guidelines
 Suggestive Implementation Strategies
 Some more guidelines
- 6. AIoT Integration in Curriculum Lesson Plans

Blockchain

- 1. Blockchain
 - 1.1.Introduction to Blockchain
 - 1.2.What is Blockchain?
 - 1.3.Key elements of Blockchain
 - 1.4. How blockchain technology works
- 2. Benefits and Challenges of Blockchain
 - 2.1.Benefits of Blockchain
 - 2.2. Challenges of Blockchain Adoption
- 3. Understanding blockchain's decentralized model
 - 3.1.Advantages of the Decentralization
- 4. Uses of Blockchain in different industries
 - 4.1.Automotive
 - 4.2. Banking and Financial Services
 - 4.3.Government
 - 4.4.Healthcare and Life Sciences
 - 4.5.Media and Entertainment Industries
 - 4.6.Supply Chain
 - 4.7.Manufacturing
- 5. Blocks, Chains and, Block header
- 6. Understanding Blockchain Consensus Algorithms
 - 6.1. What is Blockchain Consensus Mechanism?
 - 6.2.Different Consensus Algorithms



- 6.3.Proof of Work
- 6.4.Proof of Stake
- 6.5.Conclusion
- 7. Understanding the Basics of Cryptocurrency and Blockchain Wallets
 - 7.1.What are cryptocurrencies?
 - 7.2. History of Cryptocurrency
 - 7.3.Cryptocurrency Wallets
 - 7.4.Summary
- 8. Coins, Tokens, and Smart Contracts
 - 8.1.Coin and Token
 - 8.2.Smart Contracts
 - 8.3.Platform Selection for designing Blockchain Solutions
 - 8.4. Actual Platform's Speed and Scalability Rate
 - 8.5.Availability Functionality
 - 8.6.Network Adaption Rate
 - 8.7.Platform Security
 - 8.8.Public or Private
 - 8.9. Several Nodes
 - 8.10. Conclusion
- 9. Case Study: Introducing civil identity on the blockchain
 - 9.1.The Challenge
 - 9.2.Streamlining Direct Democracy
 - 9.3. The Enterprise Ethereum Solution
 - 9.4. How did it work?
 - 9.5.User experience
 - 9.6.Goals achieved
 - 9.7. Ethical challenges of Blockchain
 - 9.8.Closing thoughts

Ethical Leadership

- 1. Introduction
- 2. What is Leadership?
 - 2.1. Activity I What makes a leader?
 - 2.2. Activity Summary and Discussion
- 3. What is Ethics?
 - 3.1. Activity II The Ethical Challenge ("Value Nani")
 - 3.2. Activity Summary and Discussion
- 4. What is Altruism?
 - 4.1. Discussing Altruism
 - 4.2. Activity Summary and Discussion
- 5. What is Decisive Action?
 - 5.1. Being Ready to Take Risks
 - 5.2. Activity Summary and Discussion

Intellectual Property Rights

- 1. What is Intellectual Property?
- 2. Who can create Intellectual Property?
- 3. Why is IP Important to us?
- 4. Types of Intellectual Property Rights and How to file them.
- 5. What is a Patent? Copyright? Trademark? Geographical Indicator? Design?



Space Module

- 1. Introduction
- 2. Walkie Talkie | Telescope
- 3. Convex & Concave Lenses
- 4. Pinhole Camera
- 5. Glove Specimen Box | Rover
- 6. WeatherVane & Anemometer / Wind Speedometer
- 7. Mini Satellites
- 8. Suggested Sensors for your Satellite
- 9. Mission Control

Drones Aviation

- 1. Key features of Drone Regulations
 - 1.1. Notification of Final Regulations for Civil Use of RPAS
 - 1.1.1. Operational / Procedural Requirements
 - 1.1.2. No Drone Zones
 - 1.1.3. Operations through Digital Platform
 - 1.1.4. Enforcement Actions
 - 1.2. RPAS regulation document
- 2. Introduction to drones and their applications
 - 2.1. Definition of drones
 - 2.2. History of drones
 - 2.3. India and drones
 - 2.4. Tinkering and drones
 - 2.5. Do's and Don'ts
 - 2.5.1. Do's
 - 2.5.2. Don'ts
 - 2.6. Classification of drones based on structure
 - 2.6.1. Fixed wing structure
 - 2.6.2. Lighter than air systems
 - 2.6.3. Rotary-wing aircraft
 - 2.7. Application of drones
- 3. Dynamics of an aerial system
 - 3.1. Forces of flight
 - 3.2. Principal axes and rotation of aerial systems
 - 3.2.1. Longitudinal axis
 - 3.2.2. Lateral(transverse) axis
 - 3.2.3. Perpendicular axis
- 4. Stability and Control
 - 4.1. Equilibrium
 - 4.2. Stability
 - 4.2.1. Stable system
 - 4.2.2. Unstable system
 - 4.2.3. Neutrally stable system
 - 4.3. Control
 - 4.3.1. Roll
 - 4.3.2. Pitch
 - 4.3.3. Yaw
 - 4.3.4. Throttle
- 5. Drone Sensors
 - 5.1. What is a sensor and what is It supposed to do?



- 5.1.1. Accelerometer
- 5.1.2. Barometer
- 5.1.3. Gyro Sensor
- 5.1.4. Magnetometer
- 5.1.5. Other sensors
- 5.1.6. Distance sensors
 - 5.1.6.1. Light-Pulse Distance Sensor
 - 5.1.6.2. Radio Detection and Ranging
 - 5.1.6.3. Sonar-Pulse Distance Sensing
- 5.1.7. Time of Flight (ToF) Sensors
- 5.1.8. Thermal sensors
- 5.1.9. Chemical Sensors
- 6. Propulsion and vertical motion
 - 6.1. Propulsion
 - 6.2. Propeller
 - 6.2.1. Parameters of a standard propeller
 - 6.2.2. Propeller Materials
 - 6.3. Motors
- 7. Battery of a drone
 - 7.1. Battery
 - 7.2. Types of batteries
 - 7.2.1. Wet cell batteries
 - 7.2.2. Dry cell batteries
 - 7.3. Which batteries should we use for drones?
 - 7.3.1. High Energy Density
 - 7.3.2. C-Rating
 - 7.3.3. Voltage
 - 7.3.4. Discharge Profile
- 8. Introduction to drone programming
 - 8.1. What is programming/coding
 - 8.2. Logic in programming
 - 8.2.1. Sequential statement
 - 8.2.2. Conditional statement
 - 8.2.3. Repetitive statement
 - 8.3. What is C++
 - 8.4. Integrated Development Environment (IDE)
 - 8.5. Application Programming Interface (API)
 - 8.6. Programming a drone
- 9. How to build your multi-rotor drone
 - 9.1. Drone categories in India
 - 9.2. Components required to build a nano drone
 - 9.2.1. Frame
 - 9.2.2. Propulsion system
 - 9.2.3. Propeller guards
 - 9.2.4. Drone controller
 - 9.2.5. Flight controller
 - 9.2.6. Battery
 - 9.3. Examples of open-source Nano drones
 - 9.4. Steps to build your drone
 - 9.5. Build your own drone



SYLLABUS III – STEM MODULE

- 1. 3D Modeling
- 2. 3D Shapes
- 3. Acid Base Indicators
- 4. Adaptations
- 5. AI Activity Card
- 6. Animated Word Problems
- 7. STEM Card Area and Perimeter
- 8. Balancing Chemical Equations
- 9. Buoyancy Surface
- 10. Capillary Action
- 11. Carbon Footprints
- 12. City Planning
- 13. Coding and Design
- 14. Colours of Lights
- 15. Computational Thinking
- 16. Conductors and Insulators
- 17. Constellations
- 18. Cylinder
- 19. Decoding Mental Health
- 20. Degrees and Radians
- 21. Dispersion of Light
- 22. Dyes in Daily Life
- 23. Floatation and Sinking
- 24. Food Facts
- 25. HCF and LCM
- 26. Health and Fitness
- 27. How Do Birds Fly
- 28. Kitchen Chemistry
- 29. Learning to Code
- 30. Marine Remediation
- 31. Mathematical Patterns
- 32. Mean and Mode
- 33. Microbes and Germs
- 34. Motion and Mechanism
- 35. Nutrition Analysis
- 36. Ratio and Proportion
- 37. Reduce Reuse Recycle
- 38. Refraction and Optical Illusion
- 39. Refractive Photography
- 40. Renewable Energy
- 41. Simple Machines
- 42. Solar System | Space Junkies
- 43. Square Up
- 44. Symmetry Hunt
- 45. Things That Fly
- 46. Username Generator
- 47. Waste Management
- 48. Weather Or Not
- 49. What's In It



SYLLABUS IV – FINANCE MODULE

- 1. Essential Financial Concepts
- 2. Savings
- 3. Banking
- 4. Loans
- 5. Financial Planning
- 6. Digital Payments
- 7. Insurance
- 8. Currency
- 9. Safety, Complaints and Redressal
- 10. Building Career Awareness New

TEACHER'S TRAINING COURSE

- 1. Basics of Electronics
- 2. Basics Circuit Ohms Law
- 3. Circuits on Tinkercad
- 4. Introduction to Sensor
- 5. Introduction to Accutators
- 6. Computational Thinking
- 7. Breadboard & PCB Part 1
- 8. Breadboard & PCB Part 2
- 9. Arduino Part 1
- 10. Arduino Session-2 (Arduino With Tinkercad)
- 11. Mechanical Tools 1
- 12. Mechanical Tools 2
- 13. Introduction to 3D Printing
- 14. Design Thinking
- 15. Introduction to Raspberry Pi
- 16. Raspberry Part II
- 17. Business Pitch
- 18. Python Module
- 19. Safety Equipments
- 20. AIoT Integration
- 21. Introduction tobBlockchain
- 22. Ethical Leadership
- 23. Introduction to Drones Aviation
- 24. Introduction to Space Module
- 25. Intellectual Property Rights